3-Phase Half-Bridge Gate-Drive IC

FAN73896

Description

The FAN73896 is a monolithic three-phase half-bridge gate-drive IC designed for high-voltage, high-speed, driving MOSFETs and IGBTs operating up to +600 V.

ON Semiconductor's high-voltage process and common-mode noise-canceling technique provide stable operation of high-side drivers under high-dv/dt noise circumstances.

An advanced level–shift circuit allows high–side gate driver operation up to $V_S = -9.8 \text{ V}$ (typical) for $V_{BS} = 15 \text{ V}$.

The protection functions include under-voltage lockout and inverter over-current trip with an automatic fault-clear function. Over-current protection that terminates all six outputs can be derived from an external current-sense resistor. An open-drain fault signal is provided to indicate that an over-current or under-voltage shutdown has occurred. The UVLO circuits prevent malfunction when V_{DD} and V_{BS} are lower than the threshold voltage.

Output drivers typically source and sink 350 mA and 650 mA, respectively; which is suitable for three-phase half-bridge applications in motor drive systems.

Features

- Floating Channel for Bootstrap Operation to +600 V
- Typically 350 mA/650 mA Sourcing/Sinking Current–Driving Capability for All Channels
- Extended Allowable Negative V_S Swing to -9.8 V for Sign Propagation at V_{DD} = V_{BS} = 15 V
- Output In-Phase with Input Signal
- Over-Current Shutdown Turns Off All Six Drivers
- Matched Propagation Delay for All Channels
- 3.3 V and 5.0 V Input Logic Compatible
- Adjustable Fault–Clear Timing
- Built-in Advanced Input Filter
- Built-in Shoot-Through Prevention Logic
- Built-in Soft Turn-Off Function
- Common-Mode dv/dt Noise-Canceling Circuit
- Built–in UVLO Functions for All Channels
- This is a Pb–Free Device



ON Semiconductor®

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SOIC-28, 300 mils CASE 751BM-01



\$Y&Z&2&K FAN73896

Pin 1

- FAN73896 = Specific Device Code
 - = ON Semiconductor Logo
 - = Assembly Plant Code
 - = 2-Digit Date Code Format
 - = 2-Digits Lot Run Traceability Code

Applications

\$Y

&Z

&2

&K

- 3–Phase Motor Inverter Driver
- Air Conditioner, Washing Machine, Refrigerator, Dish Washer
- Industrial Inverter Sewing Machine, Power Tool
- General-Purpose Three-Phase Inverter

ORDERING INFORMATION

See detailed ordering and shipping information on page 15 of this data sheet.

Part	FAN73893MX	FAN73894MX	FAN73895MX	FAN73896MX
INPUT Type	Inverted	Inverted	Non-inverted	Non-inverted
V _{DDUV+} / V _{BSUV+} (Min / Typ / Max)	7.5 / 8.5 / 9.3 [V]	10.2 / 11.2 / 12 [V]	7.5 / 8.5 / 9.3 [V]	10.2 / 11.2 / 12 [V]
V _{DDUV-} / V _{BSUV-} (Min / Typ / Max)	7 / 8 / 8.7 [V]	9.7 / 10.7 / 11.4 [V]	7 / 8 / 8.7 [V]	9.7 / 10.7 / 11.4 [V]
Note	(Replacement for FAN73892MX)	_	(Replacement for FAN7389MX1)	_

Table 1. COMPARISION TABLE

TYPICAL APPLICATION DIAGRAM

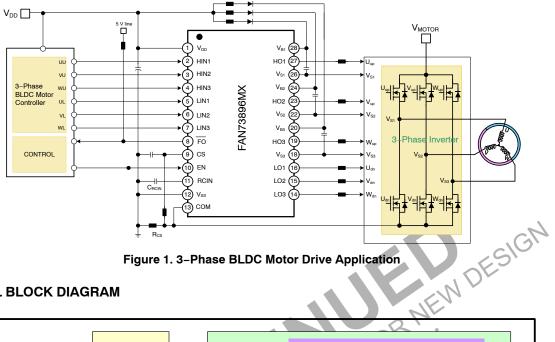


Figure 1. 3-Phase BLDC Motor Drive Application

INTERNAL BLOCK DIAGRAM

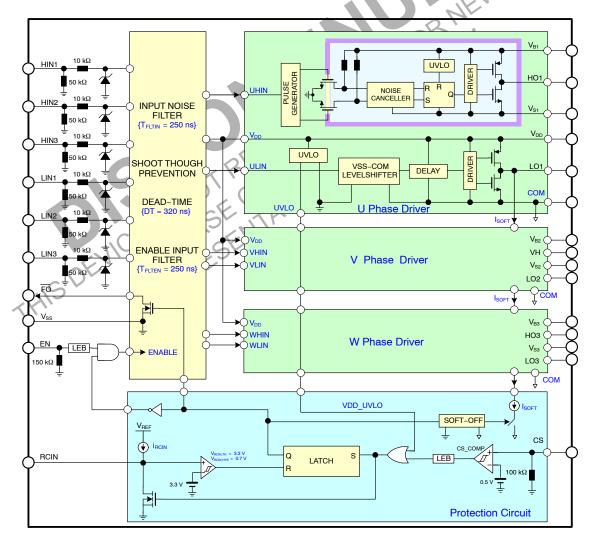
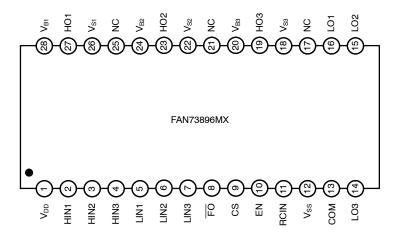


Figure 2. Functional Block Diagram

PIN CONFIGURATION



PIN DEFINITIONS

V PD CCS CS CCS CS CCS CS CCS CCS CCS							
PIN DEFIN	Figure 3. Pin Assignments						
Pin	Symbol	Description					
1	V _{DD}	Logic and low-side gate driver power supply voltage					
2	HIN1	Logic Input 1 for high-side gate 1 driver					
3	HIN2	Logic Input 2 for high-side gate 2 driver					
4	HIN3	Logic Input 3 for high-side gate 3 driver					
5	LIN1	Logic Input 1 for low-side gate 1 driver					
6	LIN2	Logic Input 2 for Iow-side gate 2 driver					
7	LIN3	Logic Input 3 for low-side gate 3 driver					
8	FO	Fault output with open drain (indicates over-current and low-side under-voltage)					
9	CS	Analog input for over-current shutdown					
10	EN	Logic input for shutdown functionality					
11	RCIN	An external RC network input used to define the fault-clear delay					
12	V _{SS}	Logic ground					
13	COM	Low-side driver return					
14	S LO3	Low-side gate driver 3 output					
15	LO2	Low-side gate driver 2 output					
16	LO1	Low-side gate driver 1 output					
17, 21, 25	NC	No connect					
18	V_{S3}	High-side driver 3 floating supply offset voltage					
19	НОЗ	High-side driver 3 gate driver output					
20	V _{B3}	High-side driver 3 floating supply					
22	V _{S2}	High-side driver 2 floating supply offset voltage					
23	HO2	High-side driver 2 gate driver output					
24	V _{B2}	High-side driver 2 floating supply					
26	V _{S1}	High-side driver 1 floating supply offset voltage					
27	HO1	High-side driver 1 gate driver output					
28	V _{B1}	High-side driver 1 floating supply					

Symbol	Parameter	Min	Мах	Unit
Vs	High-Side Floating Offset Voltage	V _{B1,2,3} – 25	V _{B1,2,3} + 0.3	V
VB	High-Side Floating Supply Voltage	-0.3	625.0	V
V_{DD}	Low-Side and Logic-Fixed supply voltage	-0.3	25.0	V
V _{HO}	High-Side Floating Output Voltage V _{HO1,2,3}	V _{S1,2,3} – 0.3	V _{B1,2,3} + 0.3	V
V_{LO}	Low-Side Floating Output Voltage VLO1,2,3	-0.3	V _{DD} + 0.3	V
V _{IN}	Input Voltage (HINx, LINx, CS, and EN) (Note 1)	-0.3	5.5	V
V _{FO}	Fault Output Voltage (FO)	-0.3	V _{DD} + 0.3	V
dV _S /dt	Allowable Offset Voltage Slew Rate	-	±50	V/ns
PD	Power Dissipation (Note 2, 3)	-	1.4	W
θ_{JA}	Thermal Resistance	-	70	°C/W
TJ	Junction Temperature	-	150	°C
T _{STG}	Storage Temperature	-55	150	°C

ABSOLUTE MAXIMUM RATINGS (T_A = 25°C unless otherwise specified)

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

All input voltage (HINx, LINx, CS, and EN) are referenced to V_{SS} and do not exceed maximum voltage rating.
 Mounted on 76.2 x 114.3 x 1.6 mm PCB (FR-4 glass epoxy material). *Refer to the following standards:*

JESD51-2: Integral circuit's thermal test method environmental conditions, natural convection;

JESD51-3: Low effective thermal conductivity test board for leaded surface-mount packages. 3. Do not exceed maximum power dissipation (P_D) under any circumstances.

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Min	Max	Unit
V _{B1,2,3}	High-Side Floating Supply Voltage	V _{S1,2,3} + 10	V _{S1,2,3} + 20	V
V _{S1,2,3}	High-Side Floating Supply Offset Voltage	6 – V _{DD}	600	V
V_{DD}	Low-Side and Logic Fixed Supply Voltage	12	20	V
V _{HO1,2,3}	High-Side Output Voltage	V _{S1,2,3}	V _{B1,2,3}	V
V _{LO1,2,3}	Low-Side Output Voltage	СОМ	V _{DD}	V
V_{FO}	Fault Output Voltage (FO)	V _{SS}	V _{DD}	V
V _{CS}	Current-Sense Pin Input Voltage	V _{SS}	5	V
V _{IN}	Logic Input Voltage (HIN1,2,3 and LIN1,2,3)	V _{SS}	5	V
COM	Low-Side Driver Return	-5	5	V
T _A	Ambient Temperature	-40	+125	°C

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

ELECTRICAL CHARACTERISTICS (V_{BIAS} (V_{DD} , $V_{BS1,2,3}$) = 15.0 V and T_A = 25°C unless otherwise specified. The V_{IN} and I_{IN} parameters are referenced to V_{SS} and are applicable to all six channels. The V_O and I_O parameters are referenced to $V_{S1,2,3}$ and COM and are applicable to the respective output leads: HO1,2,3 and LO1,2,3. The V_{DDUV} parameters are referenced to $V_{S1,2,3}$. The V_{BSUV} parameters are referenced to $V_{S1,2,3}$.

Symbol	Parameter	Condition	Min	Тур	Max	Unit
_OW-SIDE	POWER SUPPLY SECTION					
I _{QDD}	Quiescent V _{DD} Supply Current	V _{LIN1,2,3} = 0 V or 5 V, EN = 0 V	-	250	400	μA
I _{PDD}	Operating V _{DD} Supply Current	C _{LOAD} = 1 nF, f _{LIN1,2,3} = 20 kHz, rms Value	-	550	750	μA
V_{DDUV+}	V _{DD} Supply Under-Voltage Positive-Going Threshold	V _{DD} = Sweep	9.7	11.0	12.0	V
V _{DDUV-}	V _{DD} Supply Under-Voltage Negative-Going Threshold	V _{DD} = Sweep	9.2	10.5	11.4	V
V _{DDHYS}	V _{DD} Supply Under-Voltage Lockout Hysteresis	V _{DD} = Sweep	-	0.5	-	V
BOOTSTRA	APPED POWER SUPPLY SECTION					
V_{BSUV+}	V _{BS} Supply Under–Voltage Positive–Going Threshold	V _{BS1,2,3} = Sweep	9.7	11.0	12.0	V
V_{BSUV-}	V_{BS} Supply Under–Voltage Negative–Going Threshold	V _{BS1,2,3} = Sweep	9.2	10.5	11.4	V
V _{BSHYS}	V _{BS} Supply Under-Voltage Lockout Hysteresis	V _{BS1,2,3} = Sweep	-	0.5	_	V
I _{LK}	Offset Supply Leakage Current	V _{B1,2,3} = V _{S1,2,3} = 600 V	2	Y	10	μA
I _{QBS}	Quiescent V _{BS} Supply Current	V _{HIN1,2,3} = 0 V or 5 V, EN = 0 V	10	50	80	μA
I _{PBS}	Operating V _{BS} Supply Current	C _{LOAD} = 1 nF, f _{HIN1,2,3} = 20 kHz, rms Value	200	320	480	μA
GATE DRIV	YER OUTPUT SECTION	OF cell	~0 ⁷			
V _{OH}	High-Level Output Voltage, V _{BIAS} - V _O	I _O = 0 mA (No Load)	-	-	100	mV
V _{OL}	Low-Level Output Voltage, VO	I _O = 0 mA (No Load)	-	-	100	mV
I _{O+}	Output HIGH Short-Circuit Pulse Current (Note 4)	Vo = 15 V, V _{IN} = 0 V with PW ≤ 10 μs	250	350	-	mA
I _{O-}	Output LOW Short-Circuit Pulsed Current (Note 4)	V_{O} = 0 V, V_{IN} = 5 V with PW ≤ 10 μ s	500	650	-	mA
VS	Allowable Negative V _S Pin Voltage for HIN Signal Propagation to HO	IEFO	-	-9.8	-9.0	V
	UT SECTION					
V _{IH}	Logic "1" Input Voltage HIN1,2,3, LIN1,2,3		2.5	-	-	V
VIL	Logic "0" Input Voltage HIN1,2,3, LIN1,2,3		-	-	0.8	V
I _{IN+}	Logic Input Bias Current (HO = LO = HIGH)	V _{IN} = 5 V	77	100	143	μA
I _{IN-}	Logic Input Bias Current (HO = LO = LOW)	V _{IN} = 0 V	-	-	2	μA
R _{IN}	Logic Input Pull-Up Resistance		35	50	65	kΩ
ENABLE C	ONTROL SECTION (EN)					
$V_{\text{EN+}}$	Enable Positive-Going Threshold Voltage		2.5	-	-	V
V_{EN-}	Enable Negative-Going Threshold Voltage		-	-	0.8	V
I _{EN+}	Logic Enable "1" Input Bias Current	V _{EN} = 5 V (Pull–Down = 150 kΩ)	15	33	50	μA
I _{EN-}	Logic Enable "0" Input Bias Current	V _{EN} = 0 V	_	-	2	μA
R _{EN}	Logic Input Pull-Down Resistance		100	150	333	kΩ
	RENT PROTECTION SECTION	1		•		
V _{CSTH+}	Over-Current Detect Positive Threshold		450	500	550	mV
V _{CSTH-}	Over-Current Detect Negative Threshold		-	440	-	mV
V _{CSHYS}	Over-Current Detect Hysteresis		-	60	-	mV
I _{CSIN}	Short-Circuit Input Current	V _{CSIN} = 1 V	5	10	15	μA
I _{SOFT}	Soft Turn–Off Sink Current		25	40	55	mA

ELECTRICAL CHARACTERISTICS (V_{BIAS} (V_{DD} , $V_{BS1,2,3}$) = 15.0 V and T_A = 25°C unless otherwise specified. The V_{IN} and I_{IN} parameters are referenced to V_{SS} and are applicable to all six channels. The V_O and I_O parameters are referenced to $V_{S1,2,3}$ and COM and are applicable to the respective output leads: HO1,2,3 and LO1,2,3. The V_{DDUV} parameters are referenced to V_{SS} . The V_{BSUV} parameters are referenced to $V_{S1,2,3}$. (continued)

Symbol	Parameter	Condition	Min	Тур	Max	Unit		
FAULT OUT	FAULT OUTPUT SECTION							
V _{RCINTH+}	RCIN Positive-Going Threshold Voltage		2.7	3.3	3.9	V		
V _{RCINTH-}	RCIN Negative-Going Threshold Voltage (Note 4)		-	2.6	-	V		
V _{RCINHYS}	RCIN Hysteresis Voltage (Note 4)		-	0.7	-	V		
I _{RCIN}	RCIN Internal Current Source	C _{RCIN} = 2 nF	3	5	7	μΑ		
V _{FOL}	Fault Output Low Level Voltage	V _{CS} = 1 V, I _{FO} = 1.5 mA	-	0.2	0.5	V		
R _{DSRCIN}	RCIN On Resistance	I _{RCIN} = 1.5 mA	50	75	100	Ω		
R _{DSFO}	Fault Output On Resistance	l _{FO} = 1.5 mA	90	130	170	Ω		

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

4. These parameters are guaranteed by design.

DYNAMIC ELECTRICAL CHARACTERISTICS ($T_A = 25^{\circ}C$, V_{BIAS} (V_{DD} , $V_{BS1,2,3}$) = 15.0 V, $V_{S1,2,3}$ = COM, C_{RCIN} = 2 nF, and C_{Load} = 1000 pF unless otherwise specified.)

Parameter	Condition	Min	Тур	Max	Unit
Turn-On Propagation Delay	$V_{\text{LIN1,2,3}} = V_{\text{HIN1,2,3}} = 5 V_{2} V_{\text{S1,2,3}} = 0 V_{1}$	350	500	650	ns
Turn-Off Propagation Delay	$V_{\text{LIN1,2,3}} = V_{\text{HIN1,2,3}} = 0 \text{ V}, \text{ V}_{\text{S1,2,3}} = 0 \text{ V}$	350	500	650	ns
Turn-On Rise Time	V _{LIN1,2,3} = V _{HIN1,2,3} = 5 V	20	50	100	ns
Turn-Off Fall Time	V _{LIN1,2,3} = V _{HIN1,2,3} = 0 V	10	30	80	ns
Enable LOW to Output Shutdown Delay	Min 7 7 1/2h	400	500	600	ns
CS Pin Leading-Edge Blanking Time	C OP	400	650	850	ns
Time from CS Triggering to FO	From $V_{CSC} = 1 \text{ V to FO Turn-Off}$	-	850	1300	ns
Time from CS Triggering to Low–Side Gate Outputs Turn–Off	From V _{CSC} = 1 V to Starting Gate Turn-Off	-	850	1300	ns
Input Filtering Time (Note 5) (HINx, LINx, EN)		170	250	330	ns
Fault-Clear Time		-	1.30	2.35	ms
Dead Time		230	320	400	ns
Dead-Time Matching (All Six Channels) (Note 6)		-	-	50	ns
Delay Matching (All Six Channels) (Note 7)		-	-	50	ns
Output Pulse-Width Matching (Note 8)	PW _{IN} > 1 μs	_	50	100	ns
	Turn-On Propagation Delay Turn-Off Propagation Delay Turn-On Rise Time Turn-Off Fall Time Enable LOW to Output Shutdown Delay CS Pin Leading-Edge Blanking Time Time from CS Triggering to FO Time from CS Triggering to Low-Side Gate Outputs Turn-Off Input Filtering Time (Note 5) (HINx, LINx, EN) Fault-Clear Time Dead Time Dead Time Matching (All Six Channels) (Note 6) Delay Matching (All Six Channels) (Note 7)	Turn-On Propagation Delay $V_{LIN1,2,3} = V_{HIN1,2,3} = 5 \lor, V_{S1,2,3} = 0 \lor$ Turn-Off Propagation Delay $V_{LIN1,2,3} = V_{HIN1,2,3} = 0 \lor, V_{S1,2,3} = 0 \lor$ Turn-On Rise Time $V_{LIN1,2,3} = V_{HIN1,2,3} = 0 \lor, V_{S1,2,3} = 0 \lor$ Turn-Off Fall Time $V_{LIN1,2,3} = V_{HIN1,2,3} = 0 \lor$ Enable LOW to Output Shutdown Delay $V_{LIN1,2,3} = V_{HIN1,2,3} = 0 \lor$ CS Pin Leading-Edge Blanking Time $V_{CSC} = 1 \lor$ to FO Turn-OffTime from CS Triggering to FOFrom $V_{CSC} = 1 \lor$ to Starting GateOutputs Turn-OffFrom $V_{CSC} = 1 \lor$ to Starting GateOutputs Turn-OffTurn-OffInput Filtering Time (Note 5) (HINx, LINx, EN)Fault-Clear TimeDead TimeDead TimeInput All Six Channels) (Note 6)Delay Matching (All Six Channels) (Note 7)	Turn-On Propagation Delay VLIN1,2,3 = VHIN1,2,3 = 5 V, VS1,2,3 = 0 V 350 Turn-Off Propagation Delay VLIN1,2,3 = VHIN1,2,3 = 0 V, VS1,2,3 = 0 V 350 Turn-On Rise Time VLIN1,2,3 = VHIN1,2,3 = 0 V, VS1,2,3 = 0 V 20 Turn-Off Fall Time VLIN1,2,3 = VHIN1,2,3 = 0 V 10 Enable LOW to Output Shutdown Delay 400 CS Pin Leading-Edge Blanking Time 400 Time from CS Triggering to FO From V _{CSC} = 1 V to FO Turn-Off - Time from CS Triggering to Low-Side Gate From V _{CSC} = 1 V to Starting Gate - Output Filtering Time (Note 5) (HINx, LINx, EN) 170 170 Fault-Clear Time - 230 230 Dead Time Quete 7) - - Delay Matching (All Six Channels) (Note 7) - - -	Turn-On Propagation Delay VLIN1,2,3 = VHIN1,2,3 = 5 V, VS1,2,3 = 0 V 350 500 Turn-Off Propagation Delay VLIN1,2,3 = VHIN1,2,3 = 0 V, VS1,2,3 = 0 V 350 500 Turn-On Rise Time VLIN1,2,3 = VHIN1,2,3 = 0 V, VS1,2,3 = 0 V 350 500 Turn-On Rise Time VLIN1,2,3 = VHIN1,2,3 = 0 V 10 30 Enable LOW to Output Shutdown Delay 400 500 CS Pin Leading-Edge Blanking Time 400 650 Time from CS Triggering to FO From V _{CSC} = 1 V to FO Turn-Off - Time from CS Triggering to Low-Side Gate From V _{CSC} = 1 V to Starting Gate - 850 Outputs Turn-Off 1170 250 230 320 Pault-Clear Time - 1.30 230 320 Dead Time Que Attennels) (Note 6) - - - Delay Matching (All Six Channels) (Note 7) - - - -	Turn-On Propagation Delay VLIN1,2,3 = VHIN1,2,3 = 5 V, VS1,2,3 = 0 V 350 500 650 Turn-Off Propagation Delay VLIN1,2,3 = VHIN1,2,3 = 0 V, VS1,2,3 = 0 V 350 500 650 Turn-On Rise Time VLIN1,2,3 = VHIN1,2,3 = 0 V, VS1,2,3 = 0 V 350 500 650 Turn-On Rise Time VLIN1,2,3 = VHIN1,2,3 = 0 V, VS1,2,3 = 0 V 20 50 100 Turn-Off Fall Time VLIN1,2,3 = VHIN1,2,3 = 0 V 10 30 80 Enable LOW to Output Shutdown Delay 400 500 600 CS Pin Leading-Edge Blanking Time 400 650 850 Time from CS Triggering to FO From V _{CSC} = 1 V to FO Turn-Off 850 1300 Time from CS Triggering to Low-Side Gate From V _{CSC} = 1 V to Starting Gate - 850 1300 Input Filtering Time (Note 5) (HINx, LINx, EN) Incold filt 170 250 330 Fault-Clear Time 230 320 400 230 320 400 Dead Time Matching (All Six Channels) (Note 6) Incold filt - 50 50 <

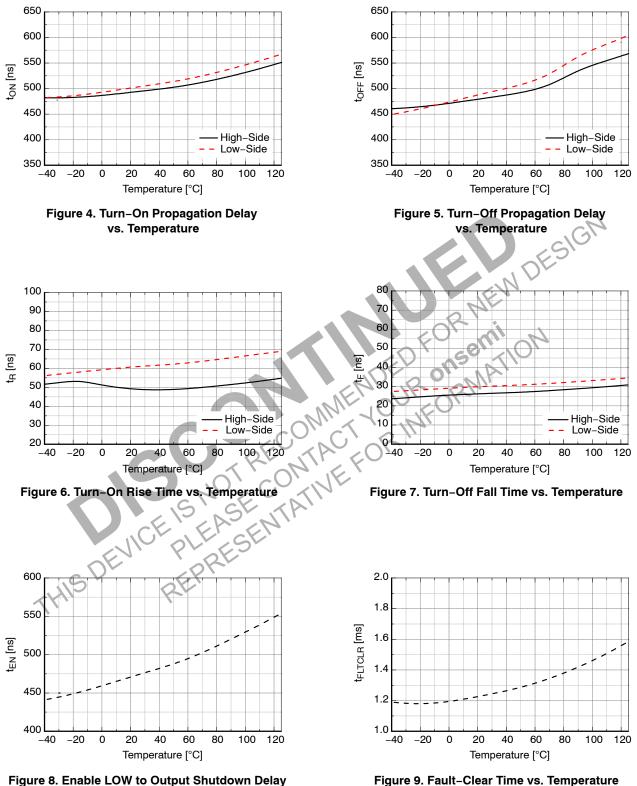
5. The minimum width of the input pulse should exceed 500 ns to ensure the filtering time of the input filter is exceeded.

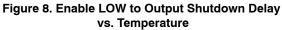
6. MDT is defined as | DT1-DT2 | referenced to 0.

7. MT is defined as an absolute value of matching delay time between High-side and Low-side.

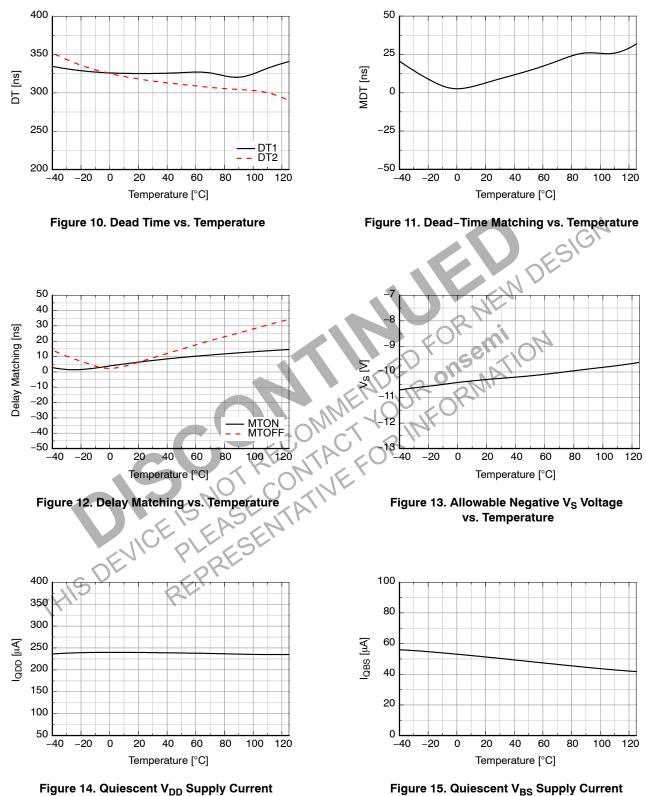
8. PM is defined as an absolute value of matching pulse-width between Input and Output.

TYPICAL CHARACTERISTICS





TYPICAL CHARACTERISTICS (continued)



vs. Temperature

vs. Temperature

TYPICAL CHARACTERISTICS (continued)

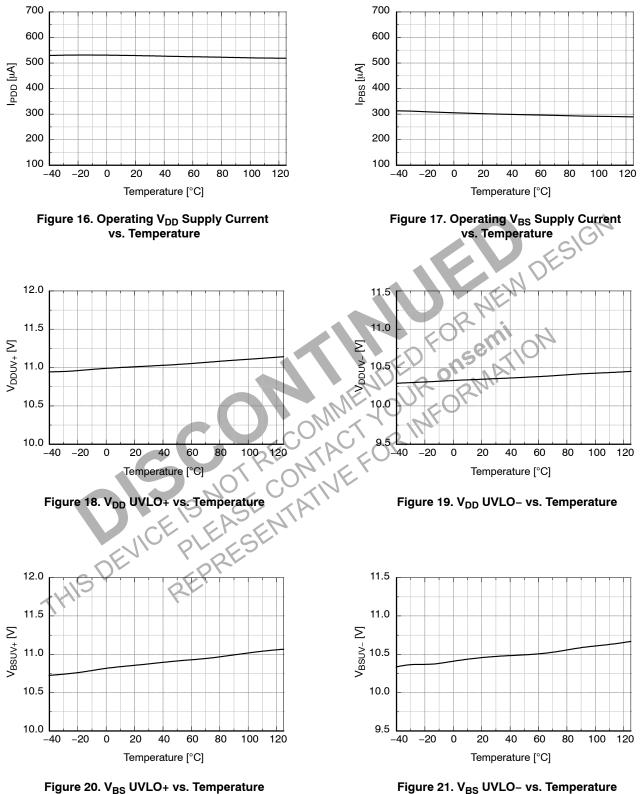
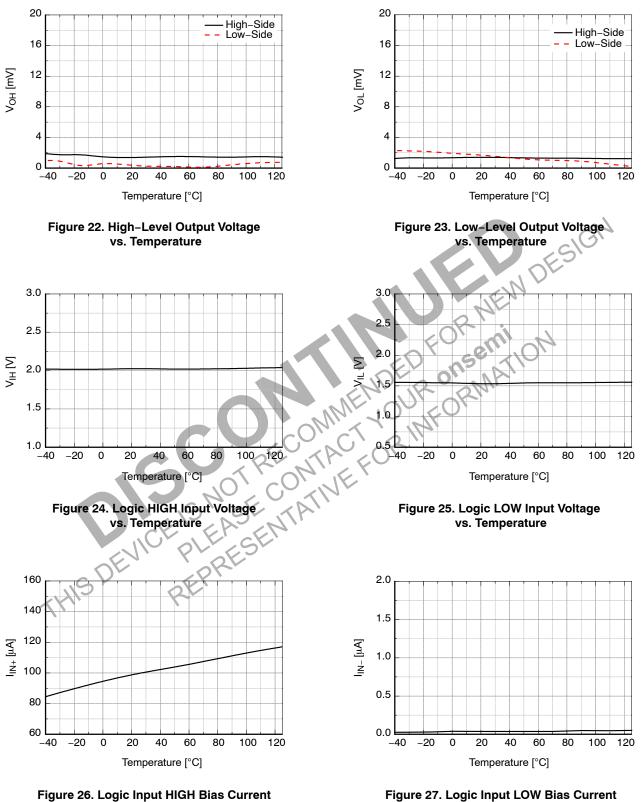


Figure 21. V_{BS} UVLO– vs. Temperature

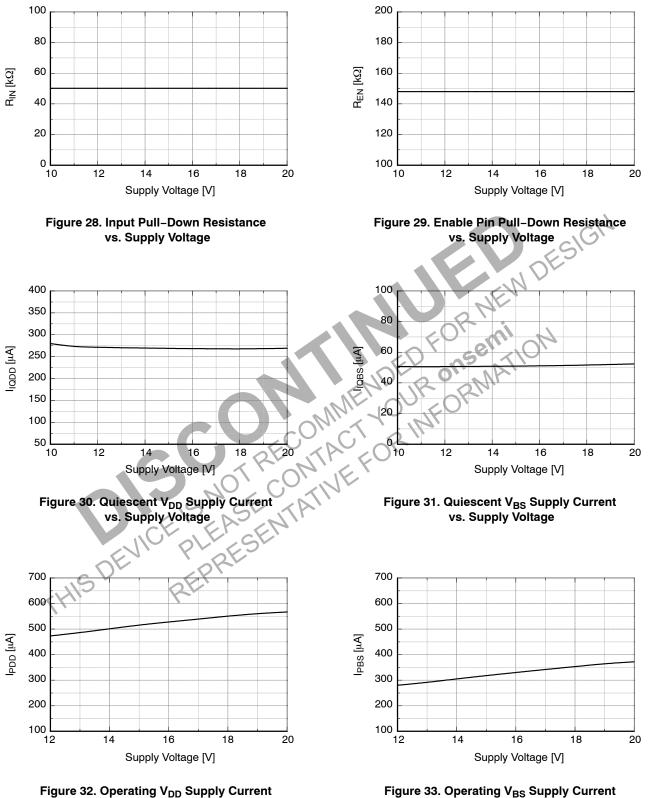
TYPICAL CHARACTERISTICS (continued)

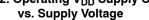


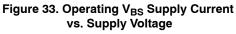
vs. Temperature



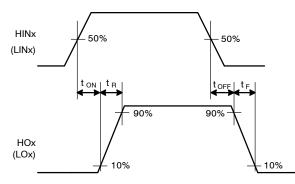
TYPICAL CHARACTERISTICS (continued)



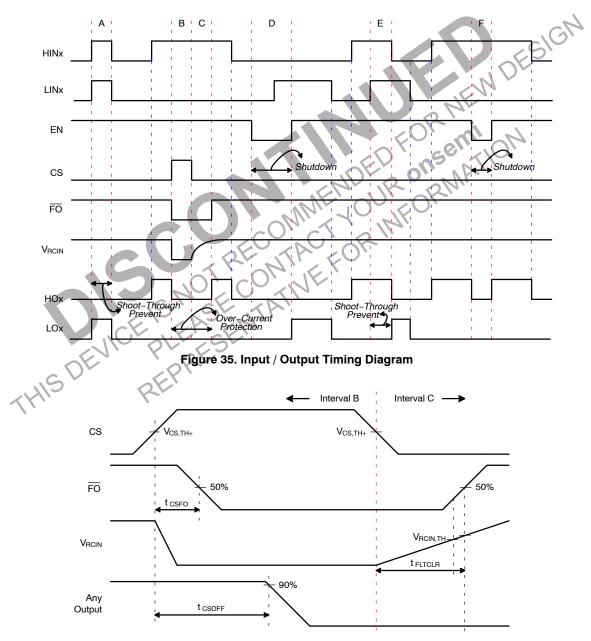




SWITCHING TIME DEFINITIONS









APPLICATIONS INFORMATION

Dead Time

Dead time is automatically inserted whenever the dead time of the external two input signals (between HINx and LINx signals) is shorter than internal fixed dead times (DT1 and DT2). Otherwise, external dead times larger than internal dead times are not modified by the gate driver and internal dead-time waveform definition is shown in Figure 37.

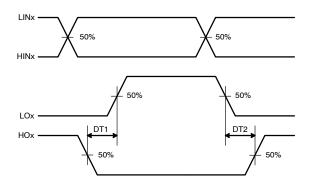


Figure 37. Internal Dead–Time Definitions

Protection Function

Fault Out (\overline{FO}) and Under-Voltage Lockout

The high- and low-side drivers include under-voltage lockout (UVLO) protection circuitry that monitors the supply voltage for V_{DD} and V_{BS} independently. It can be designed to prevent malfunction when V_{DD} and V_{BS} are lower than the specified threshold voltage. The UVLO hysteresis prevents chattering during power-supply transitions. Moreover, the fault signal (power supply voltage FO) goes to LOW state to operate reliably during power-on events when the power supply (V_{DD}) is below the under-voltage lockout high threshold voltage for the circuit (during $t_1 \sim t_2$). The UVLO circuit is not otherwise activated; shown Figure 38.

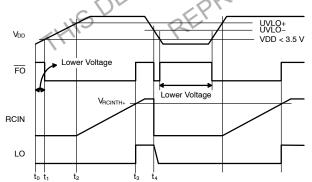
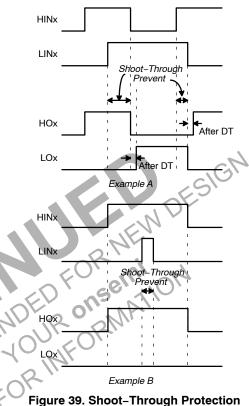


Figure 38. Waveforms for Under-Voltage Lockout

Shoot-Through Protection

The shoot-through protection circuitry prevents both high- and low-side switches from conducting at the same time, as shown Figure 39.



An interlock function is a device used to prevent both high- and low-side switches from conducting at the same time as shown in Figure 40. In most applications an interlock is used to help prevent a device from harming its operator or damaging itself by when two input signals of a same leg are activated simultaneously, only one output is activated.

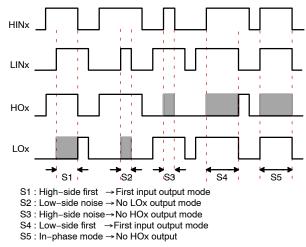


Figure 40. Interlock Function

Enable Input

When the EN pin is in HIGH state, the gate driver operates normally. When a condition occurs that should shut down the gate driver, the EN pin should be LOW. The enable circuitry has an input filter; the minimum input duration is specified by t_{FLTIN} (typically 250 ns).

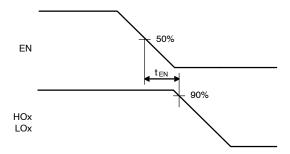


Figure 41. Output Enable Timing Waveform

Fault-Out (FO) and Over-Current Protection

FAN73896 provides an integrated fault output (\overline{FO}) and an adjustable fault-clear timer (t_{FLTCLR}). There are two situations that cause the gate driver to report a fault via the \overline{FO} pin. The first is an under-voltage condition of low-side gate driver supply voltage (V_{DD}) and the second is when the current-sense pin (CS) recognizes a fault. If a fault condition occurs, the \overline{FO} pin is internally pulled to COM, the fault-clear timer is activated, and all outputs (HO1, 2, 3 and LO1, 2, 3) of the gate driver are turned off. The fault output stays LOW until the fault condition has been removed and the fault-clear timer expires. Once the fault-clear timer expires, the voltage on the \overline{FO} pin returns to pull-up voltage.

The fault-clear time (t_{FLTCLR}) is determined by an internal current source $(I_{RCIN} = 5 \mu A)$ and an external C_{RCIN} at the RCIN pin, as shown as:

$$t_{FLTCLR} = \frac{C_{RCIN} \times V_{RCIN,TH}}{I_{RCIN}} [s]$$
(eq. 1)

The R_{DSRCIN} of the MOSFET is a characteristic discharge curve with respect to the external capacitor C_{RCIN} . The time constant is defined by the external capacitor C_{RCIN} and the R_{DSRCIN} of the MOSFET.

The output of current-sense comparator (CS_COMP) passes a noise filter, which inhibits an over-current shutdown caused by parasitic voltage spikes of V_{CS} .

This corresponds to a voltage level at the comparator of $V_{CSTH+} - V_{CSHYS} = 500 \text{ mV} - 60 \text{ mV} = 440 \text{ mV}$, where $V_{CSHYS} = 60 \text{ mV}$ is the hysteresis of the current comparator (CS_COMP), as shown in Figure 42.

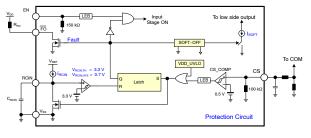


Figure 42. Over-Current Protection

Figure 43 shows the waveform definitions of RCIN, \overline{FO} , and the low-side driver; which uses a soft turn-off method when an under-voltage condition of the low-side gate driver supply voltage (V_{DD}) or the current-sense pin (CS) recognizes a fault. If a fault condition occurs, the \overline{FO} Pin is internally pulled to COM and all outputs (HO1, 2, 3 and LO1, 2, 3) of the gate driver are turned off. Low-side outputs decline linearly by the internal sink current source (I_{SOFT} = 40 mA) for soft turn-off, as shown in Figure 43.

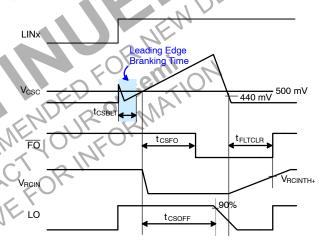


Figure 43. R_{CIN} and Fault–Clear Waveform Definition

Noise Filter

Input Noise Filter

Figure 44 shows the input noise filter method, which has symmetry duration between the input signal (t_{INPUT}) and the output signal (t_{OUTPUT}) and helps to reject noise spikes and short pulses. This input filter is applied to the HINx, LINx, and EN inputs. The upper pair of waveforms (Example A) shows input signal duration (t_{INPUT}) much longer than input filter time (t_{FLTIN}); it is approximately the same duration between the input signal time (t_{INPUT}) and the output signal time (t_{OUTPUT}). The lower pair of waveforms (Example B) shows an input signal time (t_{INPUT}) slightly longer than input filter time (t_{FLTIN}); it is approximately the same duration between input signal time (t_{INPUT}) and the output signal time (t_{OUTPUT}).

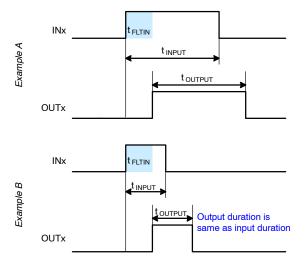


Figure 44. Input Noise Filter Definition

Short-Pulsed Input Noise Rejection Method

The input filter circuitry provides protection against short–pulsed input signals (HINx, LINx and EN) on the input signal lines by applied noise signal.

If the input signal duration is less than input filter time (t_{FLTIN}) , the output does not change states.

Example A and B of the Figure 45 show the input and output waveforms with short-pulsed noise spikes with a duration less than input filter time; the output does not change states.

Figure 46 shows the characteristics of the input filters while receiving narrow ON and OFF pulses. If input signal pulse duration, PW_{IN} , is less than input filter time, t_{FLTIN} ; the output pulse, PW_{OUT} , is zero. The input signal is rejected by input filter. Once the input signal pulse duration, PW_{IN} , exceeds input filter time, t_{FLTIN} , the output pulse durations, PW_{OUT} , matches the input pulse durations, PW_{IN} . FAN73896 input filter time, t_{FLTIN} , is about 250 ns for the high– and low–side outputs.

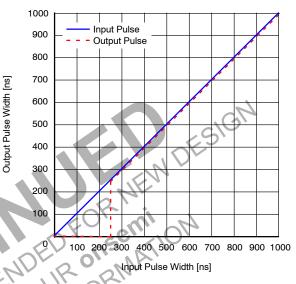


Figure 46. Input Filter Characteristic of Narrow ON



Figure 45. Noise Rejecting Input Filter Definition

ORDERING INFORMATION

Part Number	Package	Operating Temperature	Shipping [†]
FAN73896MX (Note 9)	28–Lead, Small Outline Integrated Circuit, (SOIC) (Pb–Free)	−40 to +125°C	1000 / Tape & Reel

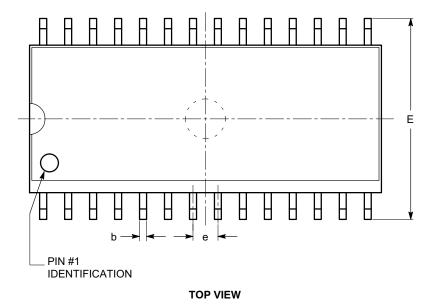
+For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

9. These devices passed wave-soldering test by JESD22A-111.

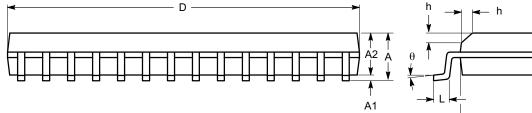


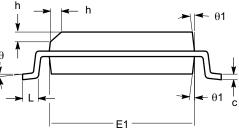
SOIC-28, 300 mils CASE 751BM-01 ISSUE O

DATE 19 DEC 2008



SYMBOL	MIN	NOM	MAX
A	2.35		2.65
A1	0.10		0.30
A2	2.05		2.55
b	0.31		0.51
с	0.20		0.33
D	17.78		18.03
E	10.11		10.51
E1	7.34		7.60
е		1.27 BSC	
h	0.25		0.75
L	0.40		1.27
θ	0°		8°
θ1	5°		15°





SIDE VIEW

END VIEW

Notes:

All dimensions are in millimeters. Angles in degrees.
 Complies with JEDEC MS-013.

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